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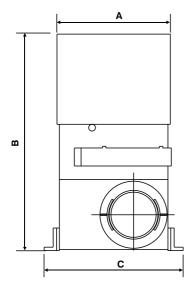
1. PRODUCT TECHNICAL DETAILS

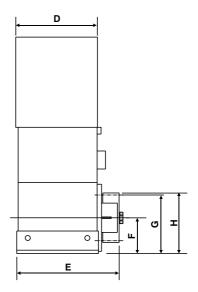
THE FAAC 746 & 844 GATE OPERATORS ARE SELF-CONTAINED UNITS CONSISTING OF A WORMGEARED ELECTRIC MOTOR , AN ELECTRONIC CONTROL CARD AND A PROXIMITY LIMIT SWITCH SYSTEM WHICH STOPS THE GATE AT THE CORRECT END POSITION.

THE UNITS HAVE A PLEASANT, MODERN DESIGN WHICH INTEGRATE HARMONIOUSLY WITH THE ENVIRONMENT OF HOME OR OFFICE.

THE FAAC RANGE ARE QUALITY PRODUCTS DESIGNED TO GIVE MANY YEARS OF TROUBLE FREE SERVICE

1.1. - Dimensions





N.B. All dimensions in mm.

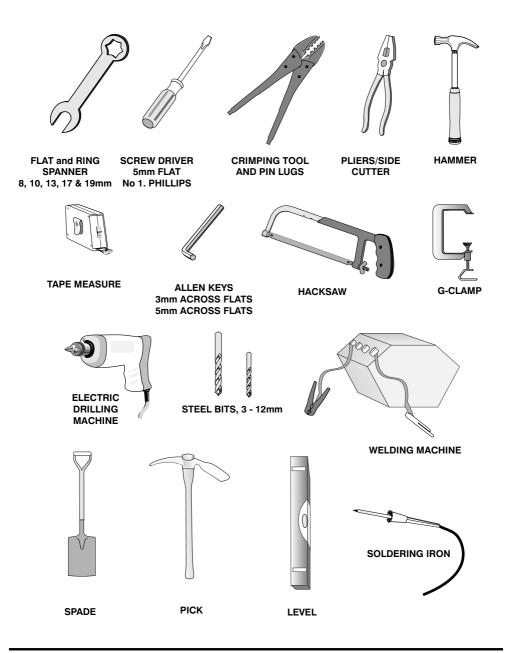
| DIMENSION | 746 20 Tooth Pinion | 844 16 Tooth Pinion | 844 20 Tooth Pinion | 844 3 Phase 16 Tooth Pinion |
|-----------|------------------------|------------------------|------------------------|--------------------------------|
| A | 275 | 280 | 280 | 208 |
| В | 312 | 385 | 385 | 385 |
| С | 210 | 209 | 209 | 209 |
| D | 155 | 158 | 158 | 158 |
| E | 191 | 191 | 191 | 191 |
| F | 64 | 64 | 64 | 64 |
| G | - | 112 | - | 112 |
| Н | 120 | - | 120 | - |

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| POWERSUPPLy 230V~ (+6%-10%) 50Hz 230V~ (+6%-10%) 50Hz ABSORBEDPOWER 300W 650W 650W ABSORBEDPOWER 300W 650W 650W CURRENTDRAW 1.5A 3.5A 3.5A CURRENTDRAW 1.5A 3.5A 3.5A MAX.STARTINGTHRUST 18kgF (220) 45khF (Z16)- 35kgF (220) IEMPERATURE RANGE 201055°C -201055°C MOTORSPEED 1400rpm 1400rpm MOTORSPEED 1400rpm 1400rpm REDUCTION RATIO 1 + 30 1 + 30 No. OF PINION TEETH 1 + 30 1 + 30 REDUCTION RATIO 220 216 (220) REDUCTION RATIO 220 216 (220) NO. OF PINION TEETH 4 MODULE 4 MODULE GATE SPEED 1 + 30 1 + 30 NO. OF PINION TEETH 220 216 (220) NO. OF PINION TEETH 216 (220) 216 (220) MOLE 200 216 (220) 216 (220) MOLE 200 216 (220) 216 (| MODEL | 746 | 844 | 844 3 PHASE |
|--|----------------------------|---------------------------|-------------------------------|--------------------------------|
| 300W 1.5A 1.5A 1.5A 1.5A 1.5A 1.5A 2.0T055°C 1400rpm 1400rpm 1.400rpm 1.400rpm 1.400rpm 1.400rpm 1.400rpm 1.400rpm 220 32 32 32 32 33 340% (see Pace 6) 1.8 35 55 35 35 30 30 | POWER SUPPLY | 230V~ (+6% - 10%) 50Hz | 230V~ (+6% - 10%) 50Hz | 380V, 3 Phase 4 wire available |
| 1.5A 1.5A 1.607 1.1400rpm 1.400rpm 1.400rpm 1.400rpm 1.400rpm 1.400rpm 1.400rpm 1.400rpm 1.810r | ABSORBED POWER | 300W | 650W | 900W |
| iT 18kgF (220) 20 T0 55°C -20 T0 55°C 1400rpm 1400rpm 1400rpm 1400rpm 220 220 220 220 220 220 220 220 220 220 220 220 220 220 1 + 30 220 220 200kg 1 + 30 220 1 + 30 20°C 20 120°C 12m/min 40% (see pade 6) 12m/min 120°C 25µF 25µF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | CURRENTDRAW | 1.5A | 3.5A | 2.5A |
| -20 TO 55°C 1400rpm 1400rpm 1 + 30 220 220 4 MODULE 4 MODULE 12m/min 12m/min 4 MODULE 4 MODULE 12m/min 12m/min 4 MODULE 4 | MAX. STARTING THRUST | 18kgF (Z20) | 45khF (Z16) - 35kgF (Z20) | 50kgF (Z16) |
| 1400rpm 1 + 30 220 220 4 MODULE 12m/min 12m/min 12m/min 40% (SEE PAGE 6) 120°C 40% (SEE PAGE 6) 1.8 LITRES 40% (SEE PAGE 6) 1.8 LITRES 20 25 LF 14kg 25 LF BIDISK IN OIL BATH 25 LF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | TEMPERATURE RANGE | -20 TO 55°C | -20 T O 55°C | -20 TO 55°C |
| 1 ÷ 30 Z20 Z20 AMODULE 12m/min 12m/min 0TECTION 120°C 40% (SEE PAGE 6) 1.8 LITRES FAAC XD 220 N 1.8 LITRES FAAC XD 220 N 1.8 LITRES FAAC XD 220 1.8 LITRES FAAC XD 220 I.8 LITRES EAC XD 220 I.8 LITRES EAC XD 220 I.8 LITRES 25 µF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | MOTORSPEED | 1400rpm | 1400rpm | 1400rpm |
| 220 4 MODULE 12m/min 0TECTION 120°C 40% (SEE PAGE 6) 40% (SEE PAGE 6) 1.8 LITRES 6 AGC XD 220 1.8 LITRES 1.8 LITRES FAAC XD 220 1.8 LITRES 5 LITRES FAAC XD 220 1.8 LITRES 5 LITRES FAAC XD 220 1.8 LITRES FAAC XD 220 25 | REDUCTION RATIO | 1 + 30 | 1 + 30 | 1 ÷ 30 |
| 4 MODULE 12m/min 0TECTION 120°C 40% (SEE PAGE 6) 40% (SEE PAGE 6) 1.8 LITRES FAAC XD 220 1.8 LITRES FAAC XD 220 1.8 LITRES FAAC XD 220 1.8 LITRES 55 LF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | Ę | Z20 | Z16 (Z20) | Z16 |
| 12m/min OTECTION 120°C 40% (sEE PAGE 6) 1.8 LITRES 1.8 LITRES 1.8 LITRES 1.8 LITRES 1.8 LITRES 5 FAAC XD 220 N IP 55 1.8 LITRES 5 JAF 8 LITRES 25 JAF 8 LITRES | RACK PITCH | 4 MODULE | 4 MODULE | 4 MODULE |
| OTECTION 120°C 40% (see Pade 6) 1.8 LITRES FAAC XD 220 N IP 55 14kg 25µF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | GATE SPEED | 12m/min | 9.5m/min (Z16), 12m/min (Z20) | 9.5m/min |
| 40% (SEE PAGE 6) 1.8 LITRES FAAC XD 220 N 1.8 LITRES FAAC XD 220 I.8 LITRES FAAC XD 220 I.8 LITRES 25 LI 25 LI 25 LI 25 LI 25 LI 25 LI BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | WINDING THERMAL PROTECTION | 120°C | 135°C | 135°C |
| 1.8 LITRES FAAC XD 220 N IP 55 14kg 25µF 25µF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE INDUCTIVE (Z20) 800kg | DUTY CYCLE | 40% (SEE PAGE 6) | 40% (SEE PAGE 6) | 40% (SEE PAGE 6) |
| FAAC XD 220 N IP 55 14kg 25μF 25μF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE INDUCTIVE (Z20) 800kg | OILQUANTITY | 1.8 LITRES | 1.8 LITRES | 1.8 LITRES |
| IP 55 14kg 25µF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | TYPE OF OIL | FAAC XD 220 | FAAC XD 220 | FAAC XD 220 |
| 14kg 25μF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | HOUSING PROTECTION | IP 55 | IP 55 | IP55 |
| 25µF BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | GEAR MOTOR WEIGHT | 14kg | 15kg | 18kg |
| BIDISK IN OIL BATH CENTURION CP81 INDUCTIVE (Z20) 800kg | STARTING CAPACITOR | 25µF | 35µF | N/A |
| CENTURION CP81 INDUCTIVE (Z20) 800kg | CLUTCH | BIDISK IN OIL BATH | BIDISK IN OIL BATH | BIDISKIN OIL BATH |
| INDUCTIVE (Z20) 800kg | CONTROL UNIT | CENTURION CP81 | CENTURION CP81 | CENTURION CP81 3 PHASE |
| . (Z20) 800kg | LIMIT SWITCH | INDUCTIVE | INDUCTIVE | INDUCTIVE |
| | MAX. GATE WEIGHT | (Z20) 800kg | (Z16) 1800kg | (Z16) 2200kg |
| | | | (Z20) 1000kg | |

2. PRODUCT INSTALLATION

2.1 RECOMMENDED TOOLS



2.2 CABLE REQUIREMENTS

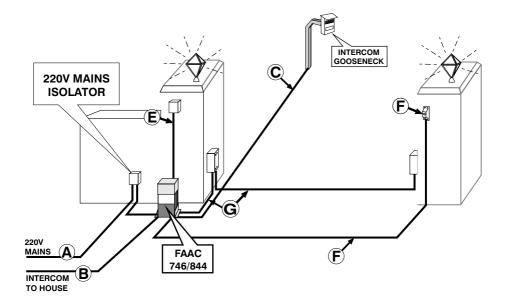


TABLE 1

| NO | DESCRIPTION | NO OF CORES | SIZE mm ² | OPTIONAL | * CABLE TYPE |
|------------|--|----------------|-------------------------|----------|--------------------------------------|
| ŧ₄ | 220V AC SUPPLY CABLE | 2 + E | | | |
| | or 380V 30 ALTERNATIVE MODEL | 4 + E | 1,5 | | NORSK IN CONDUIT OR S.W.A. |
| ‡ в | INTERCOM IN HOUSE & STATUS SIGNALLING | n1 + 6 | 0,2 | | INTERCOM IN CONDUIT |
| с | INTERCOM - GEARBOX TO GOOSENECK | n 2 | 0,2 | | INTERCOM IN CONDUIT |
| D | PILLAR LIGHTS | 2 + E | 0,5 | x | NORSK IN CONDUIT OR S.W.A. |
| Е | REMOTE RECEIVER | 3 | 0,2 | х | INTERCOM/CABTYRE/ G.P. IN CONDUIT |
| F | PEDESTRIAN KEYSWITCH | 2 | 0,2 | х | INTERCOM/CABTYRE/ G.P. IN CONDUIT |
| G | INFRA RED BEAM | 3 | 0,2 | x | INTERCOM/CABTYRE/ G.P. IN CONDUIT |

***** = CABLE TYPE IS MINIMUM RECOMMENDATION

S.W.A. = STEEL WIRE ARMOURED

- G.P. = GENERAL PURPOSE HOUSE WIRING OR PANEL FLEX
- n1 = CONSULT INTERCOM SUPPLIER FOR REQUIRED NO. OF CORES
- n2 = CONSULT INTERCOM SUPPLIER FOR REQUIRED NO. OF CORES
- **=** FOR OPTIMUM LIGHTNING PROTECTION USE SCREENED CABLE EARTHED AT BOTH ENDS

2.3 GATE REQUIREMENTS

It is important to ensure that the motor is capable of moving the gate as required. Duty cycle must be considered:

MAXIMUM DUTY CYCLE CURVE

The curve makes it possible to determine the maximum operating time with respect to the duty cycle (F).

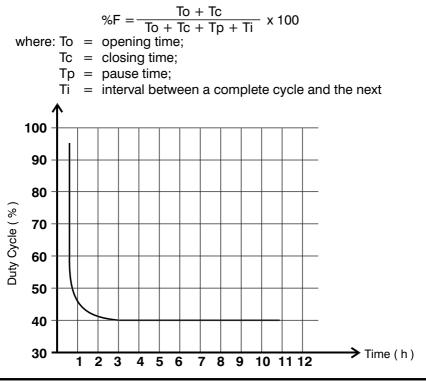
e.g., the 746 and 844 operators can work continuously at a duty cycle of 40%.

To ensure smooth running, operation should be kept within the duty area under the curve.

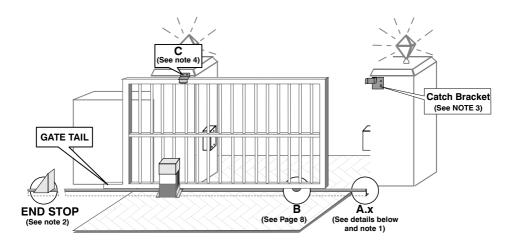
Important note. The curve was plotted on the basis of operation at a temperature of 24°C. Allow for up to 20% reduction of the duty cycle in case of exposure to direct sunlight and/or higher ambient temperatures.

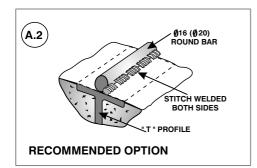
Calculating the duty cycle

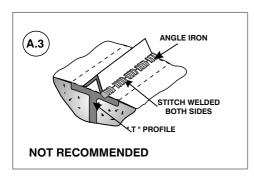
The duty cycle is the percentage of the actual operating time (opening plus closing plus pause time). The formula for calculating it is the following:



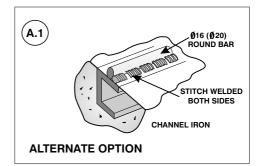
ENSURE THAT THE GATE IS FITTED WITH CORRECT END STOPS, ETC. AS SHOWN IN THE SKETCHES BELOW.







NOTE 1: The Bottom of the Round Bar (T Bar or Channel Iron) should be Level with the Ground (or not exceeding 5 mm High).



NOTE 2: Requirements of END STOP:

- Stop Gate in Fully Open Position;

- Strong Enough to Resist Full Thrust of Motor.

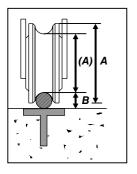
NOTE 3: CATCH BRACKET

- Secure Front of Gate When Fully Closed;
- Prevent Front of Gate from Being Lifted;
- Strong Enough to Resist Full Thrust of Motor:

- Gate Must Slide Smoothly into Catch Bracket.

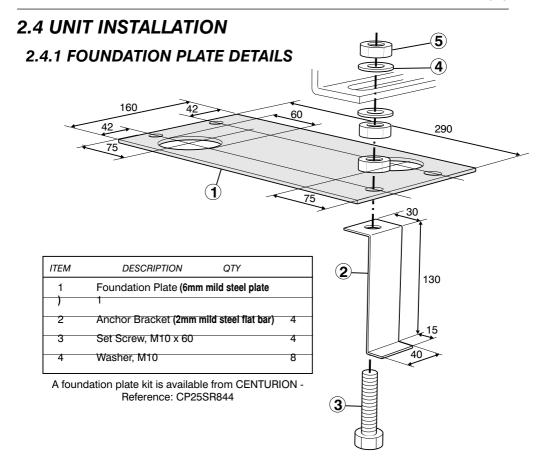
NOTE 4: GUIDE ROLLERS

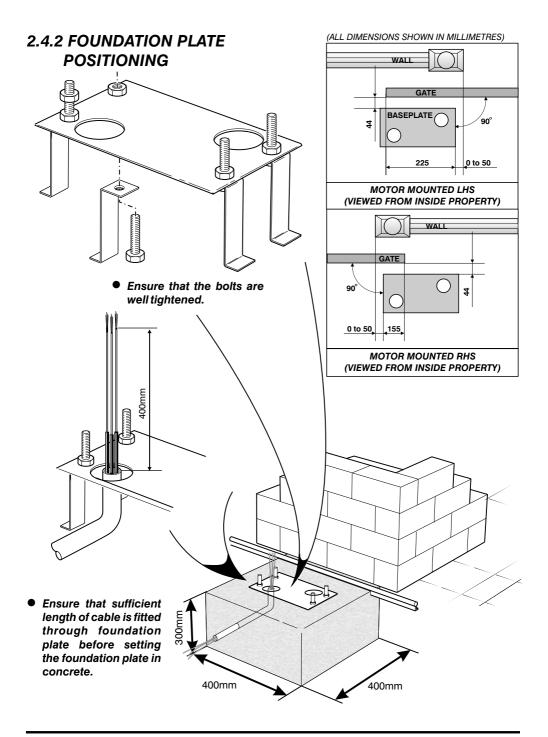
- Guide rollers must be installed. Ensure that the gap between the gate and the guide roller bracket is such that the gate cannot be lifted off the motor pinion.



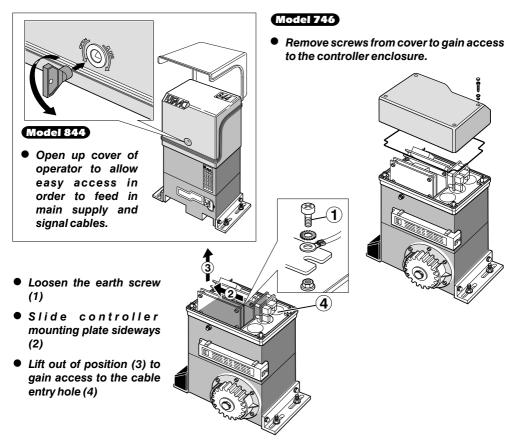
CONSULT THE ADJACENT TABLE TO DETERMINE THE CORRECT GATE WHEEL ROOT SIZE AND ROUND BAR TRACK DIAMETER REQUIRED IN RESPECT OF GATE MASS AND DUTY.

| DUTY | | | GATE | MASS | |
|------------|---|---------------------------------------|----------------|----------------------|-----------------|
| | | up to 300kg | up to 600kg | up to 1200kg | up to 2400kg |
| | | WHEEL C | UTER DIAMET | <u>TER (ROOT DI</u> | AMETER) |
| | A | 80mm | 80mm | 120mm | 190mm |
| Low | | (*65mm) | (65mm) | (100mm) | (165mm) |
| duty | | ROUND BAR TRACK DIAMETER | | | |
| | В | 16mm | 16mm | 20mm | 25mm |
| | | WHEEL OUTER DIAMETER (ROOT DIAMETER) | | | |
| | A | 80mm | 120mm | 190mm | |
| High | | (65mm) | (100mm) | (165mm) | |
| duty B | | R | OUND BAR TR | ACK DIAMETE | R |
| | | 16mm | 20mm | 25mm | |
| *V Profile | | | | | |



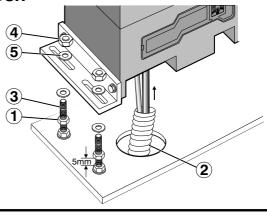


2.4.3 ACCESSING CONTROLLER MODULE



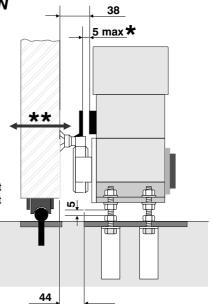
2.4.4 POSITIONING GEARBOX

- Leave at least a 5mm gap between the lower gearbox nuts (1) and the nuts which secure the foundation plate bolts.
- Feed cables (2) into the operator while lowering gearbox onto the studs (3).
- Gearbox must be firmly secured between top and bottom nuts (4) and washers (5) as shown.



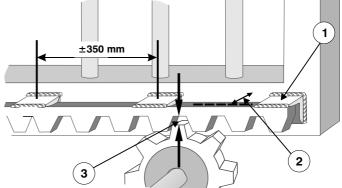
2.4.5 ADJUSTING GEARBOX POSITION

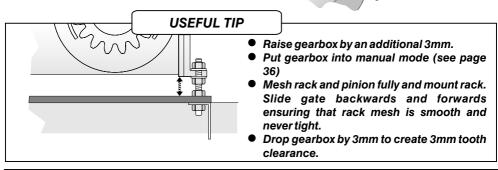
- Using the slotted holes in the angle brackets, slide the operator forwards or backwards to be in the correct position to mount the rack and the limit switch plates.
 - ★ Dimension is critical, if striker is too close it might foul and damage the inductive limit. If it is too far it might not activate the limit.
 - ★★ Check that there is little or no lateral movement of the gate, particularly when striker slides past inductive limit. See note ★ above.



2.4.6 MOUNTING OF RACK

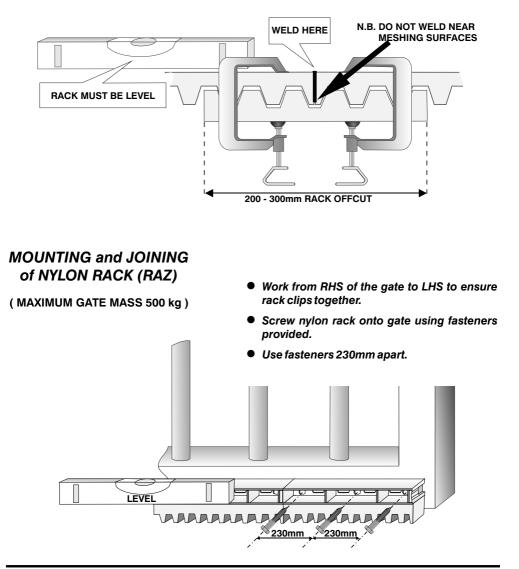
- Attach steel rack to gate using the 25x25x2mm angle brackets (1) supplied, spaced approximately 350mm apart.
- Distance between centreline of rack and edge of gate should be 25mm (2)
- Rack must be mounted level with a 2-3mm clearance (3)



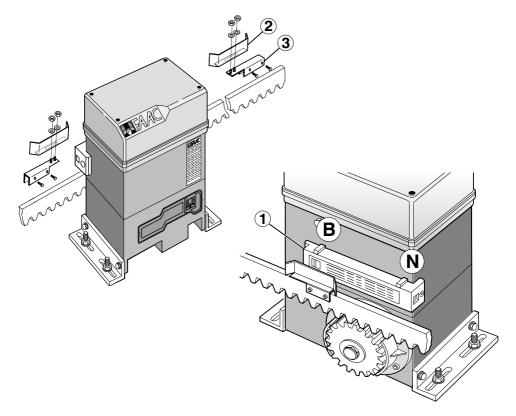


JOINING STEEL RACK

- Cut off short length of rack (approx. 200mm)
- Clamp the new pieces to the off cut.
- Weld pieces together where indicated.



2.4.7 MOUNTING AND POSITIONING LIMIT SWITCH PLATES



- The FAAC 746 & 844 operators are fitted with an inductive proximity limit switch (1). When the limit switch plate mounted to the top of the rack slides past the limit switch the operator stops the gate.
- Assemble the limit switch plate as shown, positioning the stop plate (2) centrally on the mounting studs of the support bracket (3).
- Slide the gate open leaving a 20mm gap before the end stop.
- Position the support bracket and stop plate on top of the rack with the center line of the stop plate adjacent either mark (B) or (N) of the limit switch.
- Use mark (B) if the motor is mounted on the LHS (viewed from inside the property).
- Use mark (N) if the motor is mounted on the RHS (viewed from inside the property).
- Gap between the stop plate and limit switch must be less than 5mm. Compensate for sideways movement of the gate (see page 11). Repeat steps above for closed limit using other mark.
- Refer to commissioning section 4, page 24, before testing.
- Fine adjustment of stop plates is done once the limit switch polarity (see page 27) and motor direction (see page 29) are correctly set.

3. ELECTRICAL CONNECTIONS

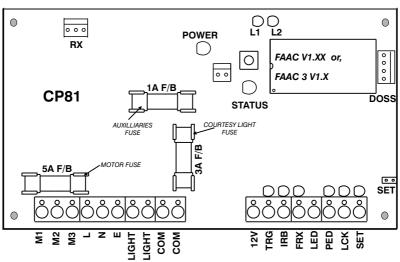
N.B.

- 1) FOR SINGLE PHASE FAAC 746/844 MOTORS THE CP81 CONTROLLER COMBINED WITH THE CP89 POWER SUPPLY BOARD IS USED;
- 2) THE THREE PHASE FAAC 844 MOTOR IS SUPPLIED WITH A CP81 CONTROLLER, CP89 POWER SUPPLY, CONTACTORS AND THERMAL CUT OUT (see Wiring Diagram, pg.16);
- DIFFERENT PIC MICROCONTROLLERS ARE USED ON 1Ø AND 3Ø VERSIONS.

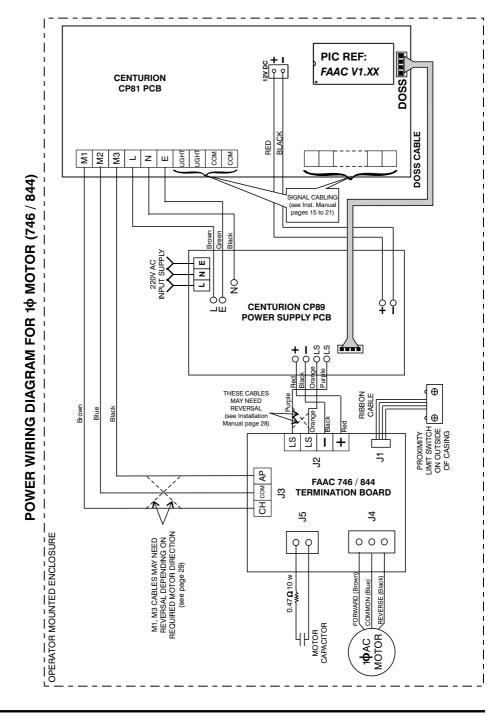
NOTES:

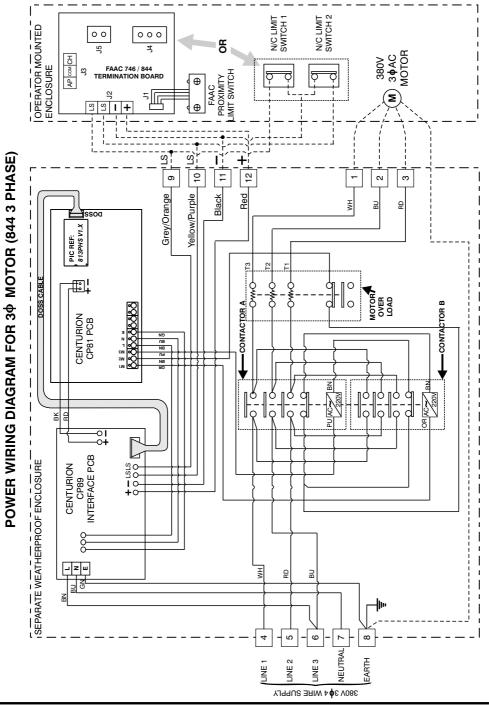
FOLLOWING ARE THE WIRING DIAGRAMS FOR THE DIFFERENT CONTROLLER ASSEMBLIES:

CP81 CONTROLLER - AC MOTOR CONTROLLER

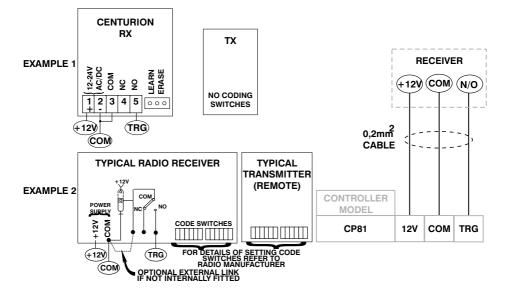


CP81 CONTROL CARD



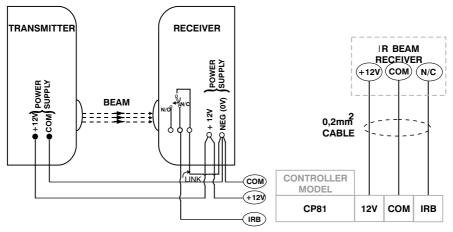


Electrical Connections continued RADIO CONNECTIONS - (REFER TO CENTURION FOR CODING DETAILS)



SAFETY BEAM

N.B. IF BEAMS ARE NOT USED THEN ENSURE THAT A LINK IS FITTED FROM "COM" TO "IRB" TERMINAL ON CONTROL CARD.

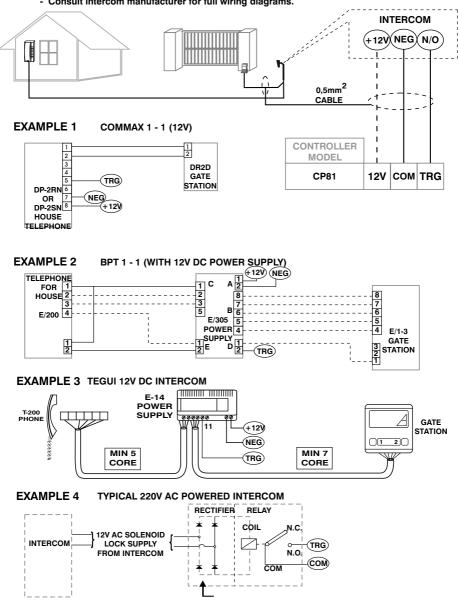


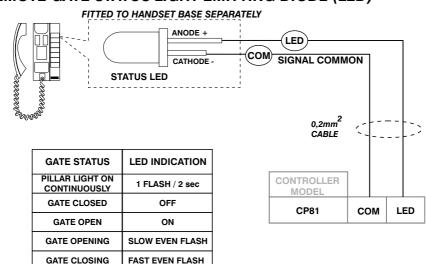
NOTE - TYPICAL SAFETY BEAM IS SHOWN. REFER TO MANUFACTURER FOR DETAILS

INTERCOM CONNECTIONS

NOTE: - Many different intercom types are available.

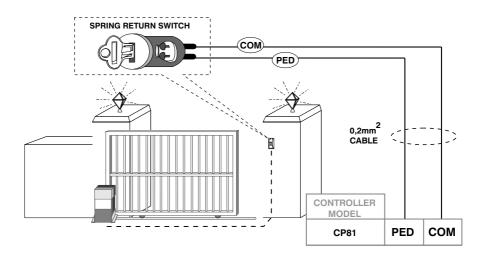
- Only signals necessary to interface intercom to Centurion's controller are shown.
- Consult intercom manufacturer for full wiring diagrams.

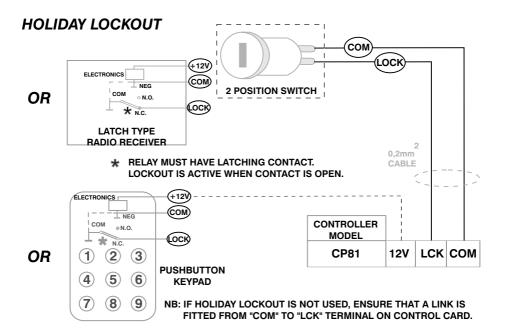




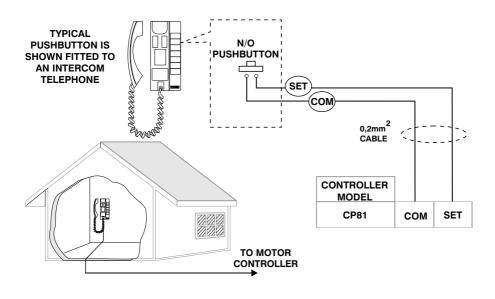
REMOTE GATE STATUS LIGHT EMITTING DIODE (LED)

PEDESTRIAN KEYSWITCH

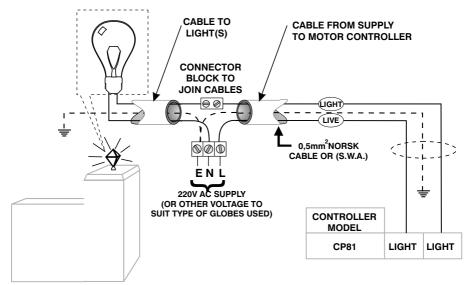




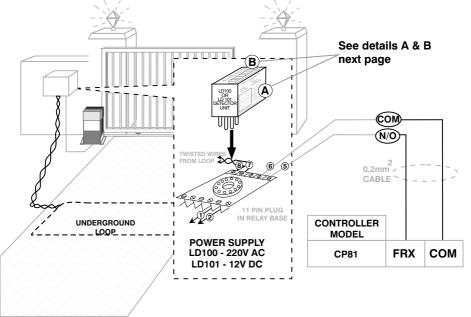
REMOTE PROGRAMME SWITCH (Activate pillar lights)



PILLAR LIGHT(S)



FREE EXIT LOOP - LD 100 OR 101 INDUCTIVE LOOP DETECTOR IS SHOWN BELOW. MODIFY WIRING IF OTHER MAKES OF DETECTORS ARE USED.



LOOP DETAILS

STANDARD FEATURES OF THE DETECTOR ARE:

- Reset Switch.

The reset switch enables the detector to be manually reset during commissioning and testing.

- This results in the detector re-tuning the sensing loop and becoming ready for vehicle detection.
- Selectable Pulse Time.
- This feature sets the length of time that the pulse relay will be energised for. 1 Second or 0.2 Second.
- Pulse Relay Selection.
- The Pulse relay may be configured to energise on detection of vehicle leaves the loop or when the vehicle leaves the loop. - Switch selectable Sensitivity. Four sensitivity settings are available on the switches to allow flexibility in configuration.

| | Selectable of | ensurvity. I Our | sensitivity settings are | | Switchic |
|---|---------------|------------------|--------------------------|-------|----------|
| 1 | High | - 0.01% | 5 | | - 0.2% |
| 2 | | - 0.02% | 6 | | - 0.5% |
| 3 | | - 0.05% | 7 | | - 1% |
| 4 | | - 0.1% | 8 | Low - | - 2% |

- Switch selectable Frequency.

Two frequency settings are available to prevent cross-talk between adjacent loops.

- Permanent Presence Option.

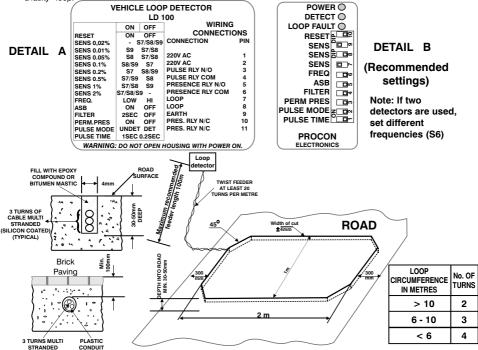
This feature ensures detection of the vehicle will be maintained when the vehicle is parked over the loop for extended periods. - Sensitivity Boost.

This feature sets the undetect level to maximum sensitivity and is used to prevent loss of detection of high-bed vehicles. - Filter Option

This option is used to provide a delay between detection of the vehicle and switching of the output relay. This delay is normally used to prevent false detection of small or fast moving objects.

- Loop Fault Indicator

This LED Indicator is illuminated when the loop is either open circuit or short circuit and is used to give a visual indication of a faulty loop.

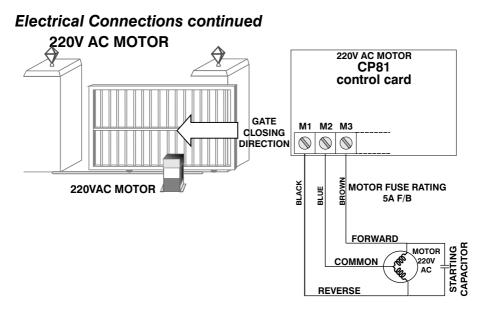


- WIRE: 1.5mm SQUARED MULTI STRANDED CABLE (USE SILICON COATED IF PLACED DIRECTLY INTO THE GROUND)

- SPACING BETWEEN TWO ADJACENT LOOPS > 2 METRES. ALTERNATE ADJACENT LOOPS USING DIFFERENT NUMBERS OF TURNS.

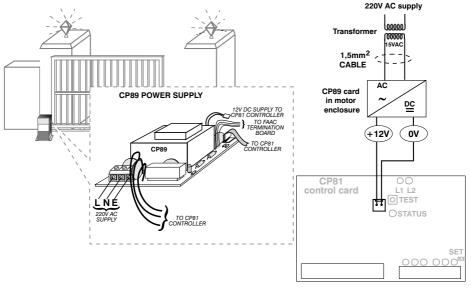
- LOOP AND FEEDER SHOULD COMPRISE ONE LENGTH OF UNJOINED WIRE. IF JOINTS ARE MADE, THEN SOLDER JOINT. - USE SCREENED FEEDER CABLE IN ELECTRICALLY NOISY ENVIRONMENTS OR WHERE FEEDER RUNS PARALLEL TO

POWER CABLES.

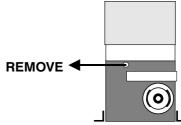


NOTE: For 3 Phase Motor connect to the separate box; see diagram inside the box. (See also page 16 for 3 Phase Motor Wiring Diagram).

TRANSFORMER POWER SUPPLY

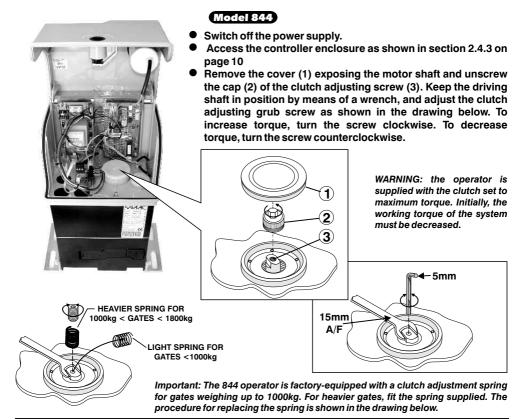


4. COMMISSIONING PROCEDURE 4.1 REMOVE OIL BLEED SCREW (IMPORTANT)



4.2 ADJUSTMENT OF ANTI - CRUSHING SYSTEM

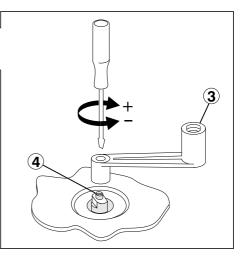
The 746 & 844 automation systems are equipped with an anti-crushing mechanical clutch which stops the opening / closing if the gate meets an obstacle during its movement. When the obstacle is removed, the gate resumes its movement until the relevant limit switch trips or the safety time (TIME OUT) is over. This torque limiter must be set in compliance with current local standards. FAAC recommends a force not to exceed 15kgF, measured on the GATE. To adjust the threshold of the anti-crushing system, proceed as follows:



Model 746

- Switch off the power supply.
- Access the controller enclosure as shown in section 2.4.3 on page 10
- Swing the controller module outward to expose the motor shaft (2) Keep the driving shaft in position with the lever supplied (3), and adjust the clutch adjusting grub screw (4) as shown in the drawing below, with a flat screwdriver. To increase torque, turn the screw clockwise. To decrease torque, turn the screw counterclockwise.

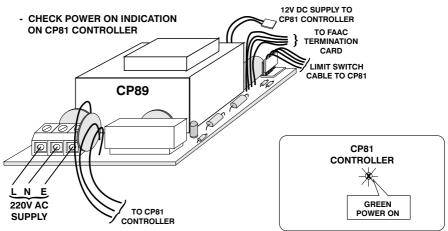




4.3 APPLYING MAINS POWER

See also Page 15 Wiring diagram for 1 \$\overline{ motor See also Page 16 Wiring diagram for 3 \$\overline{ motor } motor

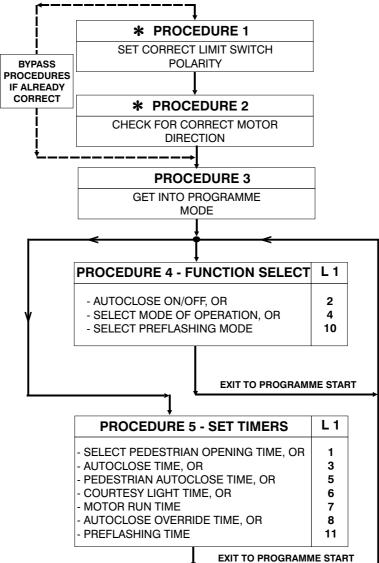
- APPLY 220V AC POWER



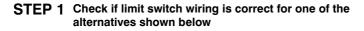
Commissioning Procedure continued 4.4 SETTING UP THE ELECTRONIC CONTROLLER

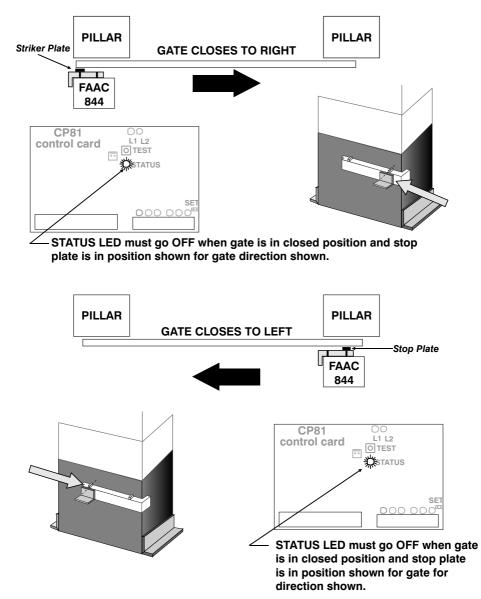
N.B. * Procedure 1 and 2 MUST be performed on initial commissioning. Procedure 3 to 5 are required ONLY if the default settings on the PCB need to be changed.

The procedure is shown in the following block diagram.



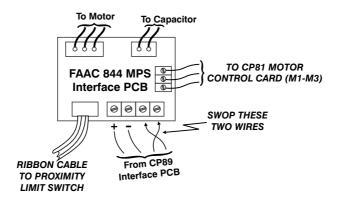
PROCEDURE 1 - SETTING LIMIT SWITCH POLARITY



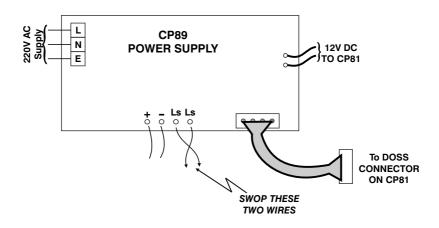


Procedure 1 - Setting Limit Switch Polarity continued

- **STEP 2** If Step 1 is incorrect then swop limit switch polarity as shown below:
 - OPTION 1 Motors fitted with FAAC termination board (See Page 15 for wiring diagram)

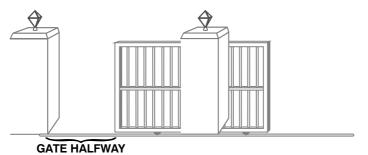


OPTION 2 Motors using CP89 power supply ONLY. (IE NO FAAC TERMINATION BOARD FITTED) (See also Page 16 for 3 Phase Motor Wiring Diagram)



Commissioning Procedure continued PROCEDURE 2 - CHECK FOR CORRECT MOTOR DIRECTION

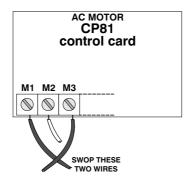
STEP 1 - Make sure Gate is in CENTRE of Travel (or that Rack is lifted off the pinion - Preferable)



STEP 2 - Trigger Motor and check that pinion rotation is correct by comparing gate direction with STATUS LED.

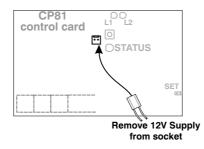
| STATUS LED | GATE DIRECTION |
|-----------------|------------------------|
| SLOW EVEN FLASH | GATE SHOULD BE OPENING |
| FAST EVEN FLASH | GATE SHOULD BE CLOSING |

- N.B. If direction is incorrect Stop Motor (or Remove Power) IMMEDIATELY, or serious damage could be done if gate runs into an End Stop.
 - STEP 3 If motor direction in Step 2 is incorrect, swop wires connected to CP81 terminals marked M1, M3.

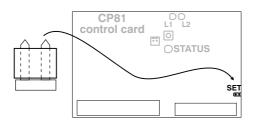


Commissioning Procedure continued PROCEDURE 3 - GETTING INTO PROGRAMME MODE

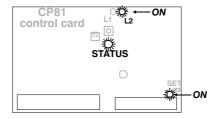
STEP 1 Remove the electronics power from the PCB. All LED's will extinguish.





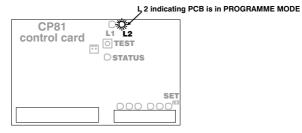


STEP 3 Reapply power (Reversal of STEP 1 above). Check that STATUS LED flashes 5 times and then " L 2 " LED must be illuminated indicating PROGRAMME MODE.

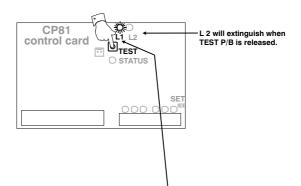


Commissioning Procedure continued PROCEDURE 4 - FUNCTIONS SELECTION

STEP 1 Ensure that PCB is in PROGRAMME MODE i.e. LED, L 2, MUST be illuminated (if not refer Procedure 3).



STEP 2 Hold TEST P/B DOWN until LED, L 1, flashes the required number of times as shown in TABLE 4.1, then release P/B.



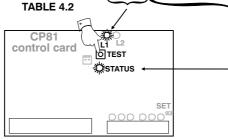
| FUNCTION TO BE SELECTED | NO. OF TIMES L1 IS FLASHING | DEFAULT STATUS |
|-------------------------|--------------------------------|-------------------|
| AUTOCLOSE ON / OFF | 2 | OFF |
| MODE OF OPERATION | 4 | STANDARD |
| INACTIVE | 7 | N/A |
| INACTIVE | 9 | N/A |
| PRE - FLASHING MODE | 10 | OFF |

TABLE 4.1

Procedure 4 - Functions Selection continued

STEP 3 Press & Hold TEST button while monitoring STATUS LED; Release the Pushbutton after STATUS LED Flashes the required number of times to select the required mode. (See Table 4.2)

| FUNCTION TO BE SELECTED | No. of times L1 is flashing | | IRED NO. (IS LED TO 2 | | |
|-------------------------|--------------------------------------|----------|------------------------------|--------|-----------|
| AUTOCLOSE ON / OFF | 2 | ON | OFF | _ | — |
| MODE OF OPERATION | 4 | STANDARD | CONDOMINIUM | PIRAC | REVERSING |
| INACTIVE | 9 | - | | | - |
| PRE - FLASHING ON / OFF | 10 | MODE 1 | MODE 2 | MODE 3 | OFF |
| | | | | | |



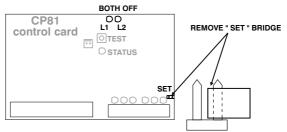
L 1 will extinguish & L 2 will illuminate allowing selection of more functions if required.

PREFLASHING MODES:

MODE 1 - LIGHT PREFLASHES AT 1 HZ, THEN ACTS AS COURTESY LIGHT MODE 2 - LIGHT FLASHES AT 1 HZ FOR PREFLASH TIME AND MOTOR RUN TIME ONLY

MODE 3 - LIGHT ON CONTINUOUSLY FOR PREFLASH TIME AND MOTOR RUN TIME ONLY

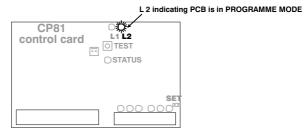
STEP 4 Exit PROGRAMME MODE, if NOT proceeding to procedure 5, by removing set bridge.



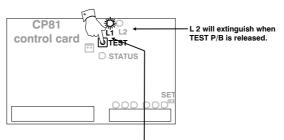
Commissioning Procedure continued

PROCEDURE 5 - SETTING DURATION OF TIMERS

STEP 1 Ensure that PCB is in PROGRAMME MODE i.e. LED, L 2, MUST be illuminated (if not refer Procedure 3).



STEP 2 Hold TEST P/B DOWN until number of flashes of LED, L1, corresponds to the TIMER to be selected as shown in TABLE 5.1, then release P/B.



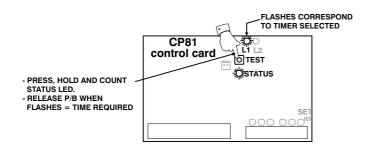
| | • | |
|----------------------|-------------------------------------|---------------------------|
| TIMER | NO. OF TIMES LED L1 SHOULD FLASH | DEFAULT TIME (SECONDS) |
| PEDESTRIAN RUN | 1 | 6 🛠 |
| AUTOCLOSE | 3 | 15 |
| PEDESTRIAN AUTOCLOSE | 5 | 5 |
| COURTESY LIGHT | 6 | 120 |
| MOTOR RUN TIME | 7 | 40 |
| AUTOCLOSE OVERRIDE | 8 | 3 |
| PREFLASHING TIME | 11 | 5 |

★ Default time of 6 seconds = Approx. 1.2m (Z20)

TABLE 5.1

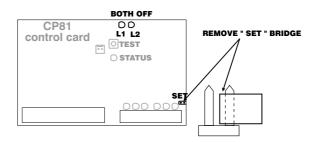
Procedure 5 - Setting Duration of Timers continued

- STEP 3 Press and Hold TEST button while counting the number of times STATUS LED flashes; Release the Pushbutton when the flashes count = time (or count) required.
 - NOTE: 1 FLASH OF STATUS = 1 second of timer duration (approx.), EXCEPT for the courtesy light timer where 1 FLASH OF STATUS = 10 seconds of timer duration (approx.).



L 1 will extinguish & L 2 will illuminate allowing selection of more timers or functions. (See Procedure 4 or 5).

STEP 4 Exit PROGRAMME MODE, if NOT proceeding to Procedure 4, by removing SET bridge.



PROCEDURE 6 - PROGRAM THE CP81 TO DEFAULT SETTINGS

- 1. REMOVE POWER.
- 2. FIT THE "SET" LINK.
- 3. CONNECT "PED" AND "FRX" TO "COM".
- 4. RECONNECT POWER. L1 AND L2 WILL ILLUMINATE.
- 5. REMOVE THE POWER.
- 6. REMOVE THE "SET" LINK AND DISCONNECT "PED" AND "FRX" FROM "COM".
- 7. THE CARD IS NOW PROGRAMMED TO DEFAULT SETTINGS AS SHOWN IN TABLES 4.1 (see page 31) AND 5.1 (see page 33) (GATE END POINTS ARE NOT AFFECTED)

4.5 TESTING THE AUTOMATION

When installation is complete, press fit the covers over the operator fixing bars.

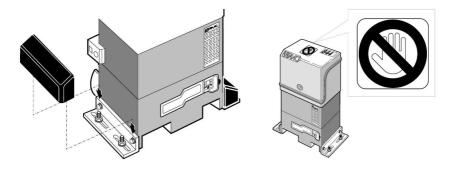
Fit the top cover to the 746 and secure with the screws and bushes supplied.

Close and lock the controller enclosure cover of the 844 operator

Affix the danger warning decal to the top cover.

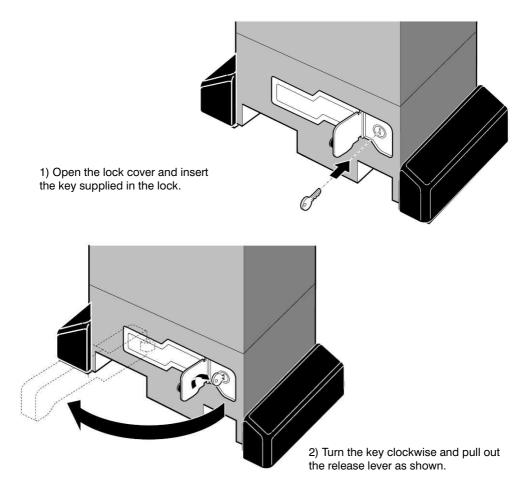
Thoroughly check operation of the automation system, including all connected accessories.

Give the customer the user guide. Explain correct use and operation of the gate motor and draw attention to the potential danger zones of the system.



5. MANUAL OPERATION

Should the need arise to operate the gate manually because of power failure or malfunction, release it by operating the releasing system as shown:



3) Open or close the gate manually.

To re-lock the system, bring the unlocking lever back to its original position. Turn the key anticlockwise, remove the key and close the lock cover.

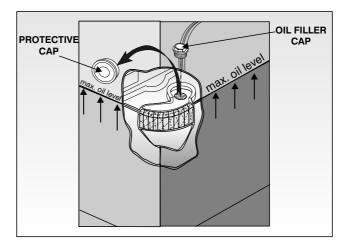
Important: Slide gate until clutch re-engages before retriggering the system.

6. MAINTENANCE

OIL LEVEL

Periodically check the oil level. For medium to low duty cycles, it is advisable to perform the check annually. Where more intensive use has occured, check every 6 months. The tank is accessed by removing the oil filler cap.

The oil level can be checked visually: it should soak the copper coil of the electric motor. If topping up is needed, use only FAAC XD 220 oil.



ANTI-CRUSHING AND SAFETY DEVICES

It is also necessary to ensure that the mechanical anti-crushing clutch is functioning and is correctly set to deliver no more than 15kgF. The safety devices installed on the system must be checked every 6 months.

7. REPAIRS

If any repair is needed, contact your authorized Centurion repair centre.



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